"Dynamic dilution exponent in monodisperse entangled polymer solutions"

Shahid, Taisir ; Huang, Q. ; Oosterlinck, F. ; Clasen, C. ; Van Ruymbeke, Evelyne

ABSTRACT

We study and model the linear viscoelastic properties of several entangled semi-dilute and concentrated solutions of linear chains of different molar masses and at different concentrations dissolved in their oligomers. We discuss the dilution effect of the oligomers on the entangled long chains. In particular, we investigate the influence of both concentration and molar mass on the value of the effective dynamic dilution exponent determined from the level of the storage plateau at low and intermediate frequencies. We show that the experimental results can be quantitatively explained by considering the tension re-equilibration process along the chains, in agreement with van Ruymbeke et al. (Macromol., 2014), i.e. by considering that the real dilution exponent \( a \) is always equal to 1, while larger values of the dilution exponent (1 < \( a \) < 1.3) found experimentally are attributed to the enhanced relaxation of the long chain extremities. Then we discuss the influence of the polymer concent...

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T. Shahid, Q. Huang, F. Oosterlinck, C. Clasen and E. van Ruymbeke

We study and model the linear viscoelastic properties of several entangled semi-dilute and concentrated solutions of linear chains of different molar masses and at different concentrations dissolved in their oligomers. We discuss the dilution effect of the oligomers on the entangled long chains. In particular, we investigate the influence of both concentration and molar mass on the value of the effective dynamic dilution exponent determined from the level of the storage plateau at low and intermediate frequencies. We show that the experimental results can be quantitatively explained by considering the tension re-equilibration process along the chains, in agreement with van Ruymbeke et al. (Macromol., 2014), i.e. by considering that the real dilution exponent $\alpha$ is always equal to 1, while larger values of the dilution exponent ($1 < \alpha < 1.3$) found experimentally are attributed to the enhanced relaxation of the long chain extremities. Then we discuss the influence of the polymer concentration on the terminal relaxation time of the solutions and how this can be modelled by the enhanced contour length fluctuation process (CR-CLF). We point out that this larger dilution effect is not only a function of concentration but also depends on the molar mass of the chains. While the proposed approach successfully explains the viscoelastic properties of a large number of semi-dilute solutions of polymers in their own oligomers, important discrepancies are found for semi-dilute entangled polymers in small-molecule theta or good solvents. Possible explanations for the differences between these sample sets are proposed, based on the comparison of their viscoelastic behavior.

I. Introduction

Today, the linear viscoelastic properties of linear entangled polymer melts are quite well understood and can be predicted on a quantitative level, based on coarse-grained models such as tube-models or slip-link models. Besides the melt state, these models can also be used to describe the properties of entangled polymer solutions or of long polymer chains diluted in a matrix of very short chains or oligomers. However, this requires accounting for constraint release mechanisms in order to describe the influence of the fast motion of shorter and oligomeric chains on the relaxation of the long chains. To this end, most of the present tube models are using the concept of dynamic tube dilution (DTD) proposed by Marrucci et al., according to which the effective diameter of the tube, $a$, which represents the constraining effect of the surrounding chains on the motion of a specific molecule, increases if the polymer concentration is reduced, as well as if part of the sample is moving fast enough so that they do not constrain the motions of the long chains anymore. Consequently, the entanglements involving these chains can be ignored and the effective average molar mass between two entanglements, $M_e$, becomes larger:

$$a(t) = \frac{a_{0,\text{melt}}}{(c \cdot \phi(t))^\alpha},$$

$$M_e(t) = \frac{M_{e,0,\text{melt}}}{(c \cdot \phi(t))^\beta},$$

with $c$, the polymer concentration, $M_{e,0,\text{melt}}$ the average molar mass between two entanglements in the melt state at time $t = 0$, $\phi(t)$, the fraction of unrelaxed polymer which still contributes to the constraining tube at time $t$, and $\beta$, the dynamic dilution exponent. As a consequence of rescaling $M_e$, the plateau modulus $G^0_N$ and the relaxation modulus $G_d(t)$ of an entangled polymer solution can be defined as:

$$G_N^0 = \frac{\rho RT}{M_e} = \frac{\rho \phi_0 RT}{M_{e,0,\text{melt}}} = G_{N,\text{melt}}^0 e^{x+1},$$

$$G_d(t) = (G_N^0 \phi(t)^x) \phi(t) = G_{N,\text{melt}}^0 e^{x+1} \phi(t)^{x+1},$$
with ρ, the density of the solution, and ρ₀ and \( G_{0,melt} \) the density and plateau modulus of the corresponding melt.

Constraint release (CR) mechanisms also affect the terminal relaxation time, \( \tau_{rel}(M) \), of the polymer solutions and in particular their reptation time, \( \tau_{rept}(M) \). The latter can be compared to the initial reptation time in the melt, \( \tau_{rept,0,melt}(M) \), by accounting for the fact that the corresponding Rouse time of an entanglement segment, \( \tau_e \), is becoming longer (since \( M_e \) is longer), while the number of entanglement segments along the chain, \( Z \), is decreasing (since \( Z = M/M_e \)):

\[
\tau_{rept}(M) = 3\tau_e Z^3 = 3\left(\frac{\tau_{e,0,melt}}{(c \cdot \phi(t))^2}\right) \left(Z_{0,melt}(c \cdot \phi(t))^3\right)^3
\]

\[= \tau_{rept,0,melt}(M)(c \cdot \phi(t))^2\]  

(5)

The \( c^3 \) scaling of the reptation time can also be found by considering that reptation time is proportional to \( L^2/D \), with \( L \), the length of the primitive path of the chain (which scales with \( c^{2/3} \)), and \( D \), the diffusion coefficient.

It must be noted that, in addition to the reptation process, a contour length fluctuation process (CLF) must be taken into account in order to determine the terminal relaxation time of the chain. This further speeds up the relaxation of the chains (see Section III).

The objective of this work is to discuss the value of the dynamic dilution exponent \( z \) in the case of long linear chains diluted in oligomers or in real solvents. While this parameter should be \( a \ priori \) equal to 1 if we consider that entanglements are binary contacts, several works have shown that, in the specific case of entangled solutions, its effectively observed value is rather equal to 4/3.\(^{14-21}\) This effective value was determined based on experimental data, by looking at the scaling of the level of the plateau modulus in the terminal regime with the concentration \( c \), based on eqn (3), where the plateau modulus can be conveniently approximated as being 3.56 times the value of the loss modulus at its maximum \( G_{max}\)\(^{18}\) (or 3.24 in ref. 14) in the case of monodisperse samples. In the following we will refer to an effective \( z \) when ever this is obtained from the scaling of \( G_{max} \) (or \( G_n \), see below) with concentration.

An explanation of the observed effective value of \( z \) close to 1.3 (or 4/3) was suggested by Colby and Rubinstein,\(^{17}\) based on the level of the second (low frequency) plateau modulus of the longer chains and its scaling with concentration. They proposed that an entanglement is created only if a fixed number of binary contacts between the chains is reached. Based on this assumption, they estimated the size of the ‘blob’ needed in order to ensure the creation of an effective entanglement at equilibrium, and they could show that such a blob size is proportional to \( c^{-2/z} \). As for the entangled solution, an effective value of \( z \) of 4/3 was also found for polymer blends composed of two monodisperse linear polymers\(^{15}\) with very different molar masses. However, in other cases such as for binary blends of linear chains with similar molar masses, or for branched molecules, the effective dynamic dilution exponent was found to be equal to 1.\(^{9,22-25}\) Then again, from the results obtained with slip-link simulations it appears that the (second) plateau modulus scales with concentration as if the dynamic dilution exponent was equal to an effective value of 4/3, despite the fact that its actual value was fixed to 1 in the model itself.\(^{7,8}\) Thus, today, there is no real consensus on what the effective value of \( z \) should be and how it is related to the actual value.

Recently, it was proposed by van Ruymbeke and co-workers\(^{11}\) that the actual dilution exponent \( z \) should be equal to 1, whatever the composition of the sample is. In order to explain a possible lowering of the plateau modulus value with concentration (that would lead, following eqn (3), to an increase of the effective \( z \) to values above 1), for solutions of longer polymer chains in a short polymer matrix the existence of an extra relaxation process was pointed out, originating from a tension re-equilibration along the chain,\(^{26}\) which takes place at the time scale of the release/re-formation of the entanglements between a long and a short chain (i.e. a ‘short–long’ entanglement), and which leads to the loss of some initial ‘long–long’ entanglements at the chain extremities, independently from the reptation/fluctuations of the long chains. This process is usually slow and does not significantly affect the relaxation of the long component, leading to a clearly observable plateau modulus of this component and consequently to an experimentally determined effective \( z \) exponent equal to 1. However, in specific cases, for example when the relaxation time of the short component is much shorter than that of the long component, this process can speed up the relaxation of the long chain and consequently the observable second plateau modulus is apparently lowered, leading to a scaling of \( G_n \) with concentration as if the effective dilution exponent \( z \) was equal to 4/3.

In order to include this mechanism in tube models, a dual approach was proposed, which considers two different pictures related to two different length scales (tube diameters) and time scales:\(^{11}\) according to the first picture the long chains are relaxing in a thin tube of diameter \( a_{0,melt} \). This thin tube is able to move and wriggle (by constraint release mechanisms) in a larger tube of diameter \( a \) defined as\(^{12,27,28}\)

\[a = \frac{a_{0,melt}}{(\nu_2)^2},\]  

(6)

with \( \nu_2 \), the volume fraction of the long chains. In such a case, the reptation and fluctuation processes take place in a thin tube composed of entanglements from both long and short chains, and the corresponding main time unit is \( \tau_{e,0,melt} \). On the other hand, according to the second picture, the thin tube is not effective anymore and the long chains are moving and relaxing in a dilated tube of diameter \( a \).\(^{29}\) In such a case, the short chains can be compared to a solvent except for the fact that an extra friction, coming from their slower motions, must be taken into account to determine how fast the long chains can move. Indeed, the long chains can only move at the time scale of the release/re-formation (or ‘blinking’) of the short–long entanglements, which slows down their relaxation processes (compared to a real solvent), and the importance of the delay depends on the relaxation time of the short chains.\(^{11}\) This requires defining a new Rouse relaxation time \( \tau_{long-long,eql} \), which represents the
necessary time for a long–long entanglement of mass $M_e (=M_{o,melt}/2^2)$ to relax by a Rouse process, and which takes into account this possible delay from the motion of the short chains. If the long chains contain at least two long–long entanglement segments, this time has been defined as\(^\text{11}\)

$$t_{\text{long–long eql}} = \max \left( \frac{t_{\text{e,melt}}}{\nu_s^{2z}}, \frac{t_{\text{short–long}}}{\nu_s^{2z}} \right), \quad (7)$$

with $\nu_s$, the volume fraction of the short chains, and $t_{\text{short–long}}$, the average relaxation time of a short–long entanglement. Thus, according to this second picture, the chains are moving in a dilated tube, which speeds up their reptation and fluctuation processes, but their ‘internal clock’, defined by $t_{\text{long–long eql}}$, can become slower than the intrinsic Rouse time of this segment, since it depends on the motion of the short chains. Therefore, depending on which process is faster and dominates, the relaxation of long chains will be better described according to the first or the second tube picture.

In ref. \textsuperscript{11}, it was shown that for binary blends of linear chains, where the second picture (\textit{i.e.} long chains moving in a dilated tube with an internal clock defined by eqn (7)) is applicable, the long chains are relaxing faster than expected from the classical tube picture, and the observable part of the second plateau modulus is effectively lowered, resulting in an effective dynamic dilution exponent $z$ larger than 1 when this is obtained from the scaling of the second plateau modulus with concentration following eqn (3). Furthermore, it was shown that in the extreme case of binary blends composed of very short unentangled chains (or oligomers), the ‘second picture’ must be considered, but with the specificity that there is no extra delay in the Rouse time of a long–long entanglement segment. Indeed, in such a case, the limiting relaxation process of a long–long entanglement is its intrinsic Rouse relaxation. Therefore, eqn (7) reduces to

$$t_{\text{long–long eql}} = \frac{t_{\text{e,melt}}}{\nu_s^{2z}}, \quad (8)$$

and an effective $z$ exponent of $4/3$ was found for a specific set of samples, even if $z$ was fixed to 1 in eqn (1)–(6) and (8).\textsuperscript{11}

Thus, by considering that the long chains in binary blends can relax according to two different length (and time) scales, which correspond to two different tube diameters, the experimental data of many binary blends could be correctly described, based on an actual $z$ value of 1.

However, several questions remain that we would like to address in the present work. In particular, we would like to test this approach on a larger set of semi-dilute or concentrated solutions of entangled polymers, diluted either in oligomers or in real solvents, in order to validate our picture. In particular, while it is expected that for such samples the second picture, which considers the long chains moving in a dilated tube, should always be active, it is in our opinion not obvious that the effective $z$ for entangled solutions should always be equal to $4/3$ (as proposed in the literature for entangled solutions\textsuperscript{14–18}). The effective $z$ obtained from the scaling of $G_{\text{max}}$ with concentration should rather depend on the equilibration state of the long chains\textsuperscript{11} in the terminal regime where the effective plateau modulus (which is approximated by $3.56 G_{\text{max}}$) is determined. Also, we would like to investigate if an effective $z$ larger than 1 is also obtained when using the value of the storage modulus detected at the higher frequency $\omega_{\text{d}}$, where the tan $\delta$ curve exhibits a minimum, a criterion that is often used to define the plateau modulus. As a last point, we would like to investigate the role of the solvent in the terminal relaxation time of the samples.

In order to address these points, a new set of model polymer solutions based on very polyvinylhloride linear chains diluted in oligomers at several concentrations has been prepared and measured, and the corresponding linear viscoelastic data are discussed, also in comparison to other sets of samples presented in the literature.\textsuperscript{10,14,19,30–32} To this end, we use our tube-based model\textsuperscript{11} to investigate, based on both experimental and theoretical data, how the value of the effective $z$ is affected by the concentration and molar mass of the chains and the nature of the solvent.

The paper is organized as follows. First, in Section II the materials used in this study, as well as the experimental techniques, are presented. Then, in Section III we present the model used for binary blends of linear chains, and reduced to the specific case of entangled polymer solutions. The results are presented and discussed in Section IV, where the experimental and theoretical data for several sets of samples are compared. The comparisons are first made for entangled polymers diluted in oligomers, and subsequently for the case of entangled polymers diluted in small-molecule solvents. Finally, the conclusions are drawn in Section V.

II. Materials and experimental details

II.1. Materials and sample preparation

The samples investigated in this work are monodisperse linear polystyrene chains either diluted in styrene oligomers or in the melt state. Some of these samples have been studied in previous works\textsuperscript{30–32} and their viscoelastic data have already been presented in the literature. These samples are listed in Table 1, together with their corresponding references. Among them, there are several monodisperse PS samples in the melt state, which will be mainly used to define and validate the material parameters used in our tube model. There is also a set of PS samples diluted in oligomers, which has been presented in ref. \textit{30} by Huang \textit{et al.}, and which has been designed in order to ensure that each of these samples contains a similar number of entanglements.

Besides these first two sets of samples, a new set of entangled solutions has been designed and prepared for the purpose of this study. These new samples consist of a very high molar mass PS polymer ($M_w = 820$ kg mol$^{-1}$) diluted in an oligomer ($M_w = 8.8$ kg mol$^{-1}$) at different concentrations, ranging from 3 wt% to 100 wt% of the polymer (see Table 1).

Both the polystyrene and oligomer were purchased from Polymer Source (Montreal, Canada). The molar mass of the
The number of entanglements are determined based on $M_e = 15$ kg mol$^{-1}$.
Indeed, these shift factors are shown in Fig. 1 at \( T \) at (i.e. their value to the shift factors vs. reference temperature can then be confirmed by comparing concentrated solutions. build the different TTS master-curves for the differently concentrated solutions is modeled based on the time marching algorithm \( t \)).

**Master-curves.** The shifted iso-\( T_g \) data measured at 130 \( C \) are then used as reference curves to shift the other experimental data measured at higher temperatures and thus to create general master-curves. It must be noted that no vertical shift has been considered here, since the range of temperature used is rather limited. In Fig. 1, all shift factors used to create the master curves are plotted against \( (T - T_g) \).

As it can be seen, when plotted in such a way, the values used for PS solutions and the melt nicely coincide. Also, their \( T \)-dependence is very close to the dependence found in ref. 30 for the other PS samples described in Table 1, which is represented in Fig. 1 by the Williams–Landel–Ferry (WLF) equation:\textsuperscript{35}

\[
\log \alpha_T = -\frac{c_1^0(T - T_{\text{ref}})}{c_2^0 + (T - T_{\text{ref}})}
\]

with \( c_1^0 = 8.99 \), \( c_2^0 = 81.53 \) K, \( T_{\text{ref}} = 130 \) °C and \( T \), the temperature expressed in °C.

The fact that all these curves superimpose also validates the factors used for shifting the data under iso-\( T_g \) conditions. Indeed, these shift factors are shown in Fig. 1 at \( T = 130 \) °C, i.e. at \( (T - T_g) \) ranging from 23.4 °C (for PS820) to 35.4 °C (for OS8.8), and they are in good agreement with the WLF equation.

### III. Tube-based model for entangled linear solutions

In this section, the viscoelastic response of the entangled linear solutions is modeled based on the time marching algorithm (TMA) that we have developed, based on the tube theory, for predicting the relaxation modulus of linear and branched entangled polymers.\textsuperscript{37–39} The main equations are summarized here below for the specific case of long linear chains of mass \( M_2 \) blended with short chains or oligomers of mass \( M_1 \). Since this approach should also correctly describe the viscoelastic properties of monodisperse chains (of mass \( M_3 \)) in the melt state, and in order to keep the model as general as possible, the equations are described as a function of the reference material parameters \( M_{e,0,\text{melt}} \) \( G_{e,\text{melt}}^{(1)} \) and \( \tau_{e,0,\text{melt}} \) of the melt state, and short–long entanglements are considered at very short times even for PS/oligo-S blends.

As mentioned in the Introduction, this approach considers the existence of two length and time scales, the first one being related to the motions of the long chains in their thin (initial) tube, while the second one is related to the motions of the long chains in their dilated tube. Since this second relaxation takes place at the rhythm of the motions of the short chains, i.e. \( \tau_{\text{short-long}} \) (see eqn (7)), the necessary time to relax one long–long entanglement segment by tension is usually delayed compared to its intrinsic Rouse time, \( \tau_{e,0,\text{melt}} \). Within this framework, using oligomers as short components represents an extreme case: the relaxation of the long chains in a thin tube (i.e. the first length scale) has a negligible effect since it is always slower than their relaxation in the dilated tube (i.e. the second length scale), this last process being not delayed by the motion of the short chains. Thus, in this specific case, the necessary time to relax one long–long entanglement segment is simply described by its minimum intrinsic value, \( \tau_{e,0,\text{melt}} \) (see eqn (8)),\textsuperscript{11} and the short–long entanglements do not play any role in the relaxation of the long chains, despite the fact that it is considered that they exist at time \( t = 0 \).

Following ref. 11, since the short chains only relax by the Rouse process, the general expression of the relaxation modulus can be described as

\[
G(t) = (\nu_1 G_{R,1}(t) + \nu_2 G_{R,2}(t)) + G_d(t).
\]

The first term of this equation describes the full relaxation of the short, unentangled chains by the intrinsic Rouse process:\textsuperscript{41}

\[
G_{R,1}(t) = \frac{\theta_0 RT}{M_1} \sum_{p=1}^{\infty} \exp\left(-\frac{2\theta^2 t}{\tau_R(M_1)}\right),
\]

with \( \tau_R(M_1) \), the Rouse time of the short chains, while the second term describes the fast Rouse relaxation of the long chains, taking place in all directions for molecular sub-chains shorter than the average molar mass between two entanglements, \( M_{e,0,\text{melt}} \), and along the tube axis (longitudinal modes) for the longer modes:\textsuperscript{4}

\[
G_{R,2}(t) = \frac{\theta_0 RT}{M_2} \sum_{p=1}^{\infty} \left\{ \exp\left(-\frac{2\theta^2 t}{\tau_R(M_2)}\right) + \exp\left(-\frac{2\theta^2 t}{\tau_R(M_2)}\right) \right\},
\]

where \( \tau_R(M_2) \) is the longest Rouse time for the long chains.
IV. Results and discussion

IV.1. Comparison between experimental and theoretical viscoelastic data

First, the viscoelastic properties of monodisperse entangled PS samples in the melt state (see Table 1) are modelled, based on the approach presented in Section III. This requires defining the values of the three material parameters corresponding to the melt state, $G_{N,\text{melt}}$, $M_{e,0,\text{melt}}$, and $\tau_{e,0,\text{melt}}$. The values of $G_{N,\text{melt}}$ and $M_{e,0,\text{melt}}$ have been set in agreement with previous works as $230$ kPa and $15$ kg mol$^{-1}$ respectively, while $\tau_{e,0,\text{melt}}$ has been fixed to $0.55$ s at the reference temperature of $130$ °C. Comparison between experimental and predicted results is shown in Fig. 2. A good agreement is found, which validates the values taken for these parameters, as well as the experimental data, which come from three different works and two different research groups.

The model is then used, without any degree of freedom using only the set melt parameters, to calculate and predict the linear viscoelastic data of the two PS solution series presented in Table 1. The comparisons between predicted and experimental data are shown in Fig. 3 and 4. While the blends presented in Fig. 3 are all based on PS820 and OS8.8, Fig. 4 presents viscoelastic data of solutions based on different molecular weight PS diluted in OS4 at different concentrations, but with a similar number of (long–long) entanglement segments, $Z_2$. It was shown in ref. 30 that the $G’$, $G''$ curves of these

![](image-url)
different solutions superimpose very well if horizontally and vertically shifted.

One can observe that the approach proposed here allows obtaining very good predictions for different masses and concentrations, spanning the whole range from concentrated and semi-dilute solutions down to only few entanglements per chain. In particular, it should be noted that this good agreement of the different plateau moduli between experiment and calculation is found when the actual dilution exponent $\alpha$ has been fixed to $\alpha = 1$ in the model.

Based on these results, several observations can be made. First, one can observe in Fig. 3 that the shape of the viscoelastic data at intermediate and high frequencies is rather complex. In particular, when the long chains are strongly diluted, we observe the appearance of different slopes in this frequency region. This can be attributed to the fact that these curves include both the relaxation of the short component (with $M_w = 8.8$ kg mol$^{-1}$) and the Rouse relaxation of the long chains up to molecular segments of mass $M_{e,0,melt}/n^2$ (see eqn (14)). This is illustrated in Fig. 5, which presents the predicted storage and loss moduli of sample PS820 diluted at 5 wt% in OS88.8, and shows the specific contributions of the different relaxation processes to the sample relaxation.

As it can be seen, the curves observed in the frequency window between 1 and 20 rad s$^{-1}$ correspond to a transition state between two Rouse domains with typical slopes of $1/2$: the first (high frequency) process includes the relaxation of both the short and the long chains and corresponds to the fast modes of Rouse, i.e. the Rouse relaxation of polymer strands shorter than $M_1$, while the second Rouse relaxation only involves the longest modes of the long chains and is associated with the relaxation of polymer strands of masses between $M_1$ and $M_e = M_{e,0,melt}/n^2$. The existence of this second frequency domain governed by Rouse relaxation shows the importance of accounting for the constraint release Rouse modes of the long chains, taking place up to the long–long entanglement segments of mass $M_e$, in order to properly capture the relaxation behavior of such blends with a large difference in $M_w$.

Though this might be obvious for the case of polymer solutions, this point becomes more delicate for binary blends of short and long molecules. Indeed, as described in Section III, this Rouse-like relaxation, which allows the long chains to move from a thin tube to a dilated tube, is usually described by the constraint release Rouse process (CRR) through eqn (14). However, this requires accurately defining the relaxation state of the chains at the time the CRR becomes active. While it is easy to determine this state in the case of long chains diluted in oligomers (by imposing $\phi(t = \tau_c) = 1$), for longer short chains the starting time of CRR and the corresponding relaxation state are not known a priori.

In Fig. 5, one can also observe that the rubbery plateau is quite low and not well defined. This can be understood based...
on the fact that when diluted to 5 wt%, sample PS820 only contains an average of 2.7 entanglement segments per chain, which is at the limit of the entangled state. In the terminal zone, the chains are therefore moving by CR-CLF in a very diluted tube. In order to observe an actual (rubbery) plateau, the concentration of sample PS820 must be at least 10 wt% (see Fig. 3).

As seen in Fig. 2 for the monodisperse samples, the high frequency data are not accurately captured by the model. This is due to the contribution of the terminal tail of glassy relaxation, which is not included in the model. On the other hand, the discrepancy observed in Fig. 4 at high frequency has two different origins: in addition to the contribution of glassy relaxation, a large part of the disagreement comes from the fact that our model predicts slower Rouse relaxation of the oligomers when compared to the experimental results. This cannot be corrected by considering another value for the material parameter $\tau_{\star,0,\text{melt}}$ (used to define the intrinsic Rouse time of the oligomers) since this would strongly affect the other data. However, since this discrepancy is observed only at very high frequency, it does not influence the curves around the rubbery plateau, i.e. in the frequency area where we would like to discuss the results and the value of the effective dilution exponent.

The good agreement found between experimental and theoretical curves allows us to take advantage of the model for further investigating how the effective (i.e. experimentally determined from the scaling of $G_{\max}''$ or $G_{\delta}$ with $c$) value of $\alpha$ varies with the sample composition. This is the objective of the next section.

IV.2. Influence of concentration on $G_{\theta}^0$, $G_{\delta}$, $G_{\max}''$ and on the effective $\alpha$

As already mentioned, the plateau modulus of the different blends in Fig. 2–4 is well described by the model in which the plateau modulus of these blends in Fig. 2–4 is well described by the model in which the effective value of $G_{\max}$ of the blends is determined for low concentrations of PS in oligomers since there is no clear maximum in the corresponding loss modulus curves, due to the overlap between the constraint release Rouse process and terminal relaxation of the chains (see Fig. 5). Only the plateau of the PBD samples could be measured, since the long chains are much more entangled than the PS long chains. On the other hand, $G_{\delta}$ could be measured only for the samples with experimental data in the intermediate and high frequency regions.

Fig. 6 reveals important features:

- From the comparison between $G_{\max}''$ and $G_{\delta}$, we can see that the $G_{\max}''$ values are indeed around a factor of 3.56 lower than the values of $G_{\delta}$. Also, we observe that the $\alpha$-dependence of $G_{\max}''$ and $G_{\delta}$ is very similar and that they both differ from the real plateau modulus $G_{\theta}^0$ (represented by the solid line in Fig. 6a); this discrepancy increases with decreasing polymer concentration. From this result, we conclude that the CR-CLF process can already affect the viscoelastic properties at the intermediate frequency $\omega_0$. Thus, the $G_{\delta}$ values obtained from the $\tan \delta$ method, cannot be used to determine $G_{\theta}^0$ for polymer/oligomer blends since it is already influenced by the fast tension equilibration process.

- We also see that the $G_{\max}''$ data are a little more scattered than the $G_{\delta}$ data. This is most probably due to the fact that $G_{\max}''$ is much more sensitive to polydispersity than $G_{\delta}$.

Results obtained for the two sets of solutions are shown in Fig. 6. The theoretical $G_{\delta}$ values have also been determined and are represented by the cross symbols in Fig. 6a.
show a transition from \( c^2 \) to \( c^{2.5} \)-dependence of their plateau values. This demonstrates that the value of the effective \( \alpha \) determined from either \( G_{\text{max}}'' \) or \( G_\delta \) is not a constant and depends on the concentration.

- Looking at the \( G_\delta \) extracted from both the experimental and the theoretical curves (see Fig. 6a), it is interesting to note that the set of PS/OS4 blends prepared from different molecular weight PS samples in order to keep \( Z_2 \) constant (set 2, see the red symbols) show \( c^2 \)-dependence also at lower concentrations, while this is not the case for the other blends, made from long chains with a specific, constant molar mass and varying concentrations. In particular, the value of \( G_\delta \) of PS3200 diluted to 13 wt% is well above the \( G_\delta \) found for a solution of 13 wt% of PS820. From this observation, one can conclude that the effective \( \alpha \) determined from \( G_\delta \) (at intermediate frequency) is not only a function of concentration, but also seems to depend on the molar mass of the chain.

This is further illustrated in Fig. 7, which compares the viscoelastic response of two solutions of PS chains, both at the same concentration of 10 wt%, but with chain molar masses of either 820 kg mol\(^{-1}\) or 3900 kg mol\(^{-1}\). Despite the fact that they are diluted to the same concentration and thus have the same entanglement density, it is obvious that the value of \( G_\delta \) is much lower for sample PS820 (which contains 6 long–long entanglements) in comparison to the \( G_\delta \) value of the PS3900 sample (which contains around 28 long–long entanglements).

From these observations, a global picture can be drawn: while the effective value of \( \alpha \) in binary blends of long and short linear chains must be determined from moduli in the frequency range close to the terminal relaxation of the long chains,\(^{11}\) for polymer/oligomer blends a larger effective \( \alpha \) can also be determined from moduli at higher frequencies, with no significant difference between the \( c \)-dependence of the values of \( G_{\text{max}}'' \) and \( G_\delta \). This is due to the fact that, in the case of polymer/oligomer blends, the tension equilibration process, which is modelled here by the CR-CLF process, is very fast since it does not include any delay due to the motions of the short component (see eqn (7) and (8)), and the long chains can explore their dilated tube as fast as their intrinsic Rouse process allows. Since these fast Rouse motions are already taking place at times shorter than the inverse of the frequency \( \omega_0 \) where \( G_\delta \) is determined, the effective \( \alpha \) at intermediate frequency is found to be larger than 1.

If we consider that a large value of the effective \( \alpha \) is related to the tension equilibration process, as suggested in this work, one can easily explain that its value can vary between 1 (no influence of the CR-CLF) and 4/3 (fully equilibrated long chains\(^{17}\)), depending on both concentration and molar mass of the long chains. Indeed, from eqn (16) it is expected that the importance of the CR-CLF process increases with decreasing chain length or the concentration, i.e. the effective \( \alpha \) increases with a decreasing number of long–long entanglements per chain, \( Z_2 \). This \( Z_2 \) dependence of the effective \( \alpha \) is consistent with the \( c^2 \)-dependence found for \( G_\alpha \) with the second set of PS–OS blends, for which \( Z_2 \) was kept constant for all concentrations,\(^{30,31} \) in such a case the importance of the CR-CLF process is exactly the same for all the samples since they all have a constant number of entanglements. Thus, they are all characterized by a similar effective \( \alpha \) and the slope of the \( G_\delta \) values continues to scale with \( c^2 \). In contrast, the dependence of \( G_\delta \) for the PS820/OS8.8 blends shows a power law which is relatively well defined by a slope of 7/3 at low concentrations:\(^{30,31} \) on diluting PS820 in oligomers, the number of (long–long) entanglement segments decreases; this enhances the CR-CLF process, which is already observed at intermediate frequency since it is not delayed by the short chains. As a consequence, the difference between \( G_\delta \) and \( G_{\text{R}}^0 \) increases when PS820 is diluted in oligomers.

Thus, the tension equilibration process allows us to explain the non-constant value of the effective \( \alpha \) found experimentally from \( G_{\text{max}}'' \) and \( G_\delta \) as well as its dependence on concentration and molar mass. According to the CR-CLF process, its value should depend on \( Z_\alpha \), which is further validated in Section IV.3.

Another consequence of this fast CR-CLF process is that for such blends, \( G_\delta \) cannot be considered as a good approximation of the plateau modulus \( G_{\text{R}}^0 \), which scales with \( c^2 \) for all concentrations (as defined in our model). This is illustrated in Fig. 7, which shows the storage modulus corresponding to \( G_\delta \) for the two blends, and compares this value with the real plateau modulus \( G_{\text{R}}^0 \) determined by removing the contribution of the high frequency Rouse relaxation as well as the CR-Rouse modes (see eqn (14)) from the theoretical curves.\(^{46,48} \) It is seen that, due to the overlap between Rouse relaxation and the CR-CLF process, the minimum of the tan\( \delta \) curve is found at a rather low frequency \( \omega_0 \) (see the X symbols), at which the sample has already partially relaxed by tension equilibration.

**IV.3. Influence of \( Z_2 \) on the terminal relaxation time, CR-CLF process and effective \( \alpha \)**

As described in Section IV.2, it seems that the value of the effective \( \alpha \) depends on the importance of the CR-CLF process:
the more the chains are able to relax by CR-CLF before their terminal relaxation, the larger is the effective $\alpha$, which is usually determined based on the scaling of $G''_{\text{max}}$ with concentration, but which can also be determined from $G_\alpha$ in the specific case of polymer/oligomer blends. Thus the transition between an effective $\alpha$ of 1 (negligible effect of CR-CLF) and 4/3 (fully equilibrated chains\textsuperscript{17}) could, in principle, take place at any possible concentration, depending on the entanglement state of the long chains, $Z_2$. In this section, we first try to point out the existence and importance of the CR-CLF process as a function of $Z_2$, based on the experimental terminal relaxation time of the solutions, and then relate this process to the effective $\alpha$ determined from $G_\alpha$.

As mentioned in the Introduction, the terminal relaxation time of the solutions is expected to be a function of both reptation and CR-CLF processes. Since the real dynamic dilution exponent $\alpha$ is equal to 1, the reptation time of the monodisperse long chains diluted in oligomers (or theta solvent) should therefore scale with concentration (see eqn (17));

$$\tau_{\text{rept, 0}}(M_c) = \tau_{\text{rept, 0, unid}}(M_c) C_1.$$  

Therefore, by comparing this theoretical reptation time with the experimental terminal relaxation times of these samples, one should be able to extract the importance and scaling of the CR-CLF process. In order to do so, the experimental terminal relaxation time $\tau_{\text{rel}}$ must be determined. This is achieved by superimposing terminal slopes of 1 and 2 on the experimental loss and storage moduli curves in the terminal regime and by defining $\tau_{\text{rel}}$ as the inverse of the frequency at which these two lines cross each other.\textsuperscript{3}

Terminal and reptation times are compared in Fig. 8a as a function of the concentration, and in Fig. 8b as a function of the number of long–long entanglement segments, $Z_2$, which leads to several observations:

First, one can clearly see that reptation alone is not enough to explain the relaxation of the samples: as expected, the contour length fluctuation (CLF) process (for the monodisperse PS samples) and CR-CLF (for the solutions) are needed in order to explain the shorter terminal relaxation times. Also, the ratio between terminal and reptation relaxation time cannot be seen as a simple function of concentration; it is rather a function of the number of long–long entanglement segments along the long chains, $Z_2 = (Z_{2,0} \cdot c)$. Indeed, as shown in Fig. 8b, all the data superimpose when plotted in this way and create a master curve, except for the PBD925/DOP solutions, which are discussed in Section IV.A.

In Fig. 8b, a transition is observed around $Z_2 = 20$, from a terminal time dominated by reptation at high $Z_{2,0}$ towards much shorter terminal times at low $Z_2$, for which another scaling is observed: the terminal relaxation time of the diluted chains containing less than 20 long–long entanglement segments is found to scale with $(Z_{2,0}^{\alpha})^{1/2} Z_2$, i.e. with $(c Z_{2,0}^{\alpha})$. This scaling is identical to the scaling of the CR-CLF process (see eqn (16)) and therefore validates this relaxation mechanism and demonstrates its importance for moderately entangled linear chains diluted in oligomers. In fact, for such chains the reptation process (taking place in a tube only formed by the long–long entanglements) becomes very slow compared to the CR-CLF process, and its influence becomes negligible.

Similarly to the terminal relaxation time, the $c$-dependence of $G_\alpha$ data can be rationalized when they are plotted as a function of $Z_2$. This is illustrated in Fig. 9, based on theoretical moduli: the values of $G_\alpha$ determined from theoretical storage and loss moduli are shown in Fig. 9a for three different molar masses and for a large range of concentrations, while Fig. 9b shows the same data but plotted as a function of $Z_2$.

As it can be seen in Fig. 9a, the $c$-dependence of $G_\alpha$ varies with the molar mass of the chains, as it has been observed from the experimental data. Furthermore, it also depends on the range of concentrations considered. However, when plotted as a function of $Z_2$ (see Fig. 9b), one can see that, despite the different levels of $G_\alpha$ (which comes from the different concentrations (see eqn (3))), all the curves show a transition from an effective $\alpha$ equal to 1 to a larger value at the same number of entanglements, corresponding to around 12 entanglements. While the fact that the effective $\alpha$ tends to 4/3 at low concentration cannot be determined from the equations, this scaling is clearly observed in Fig. 9.

While the CR-CLF process starts to affect the terminal relaxation time around $Z_2 = 20$, it starts to have a large influence on $G_\alpha$ only at $Z_2 = 12$. This difference in the transition can be understood from the fact that $G_\alpha$ is less sensitive to $Z_2$ than the CR-CLF process (see eqn (16)). These results suggest that, in order to experimentally determine an effective $\alpha$ equal to 1 from $G''_{\text{max}}''$ or $G_\alpha$, the diluted chains should at least conserve 12 (long–long) entanglements. This is in good agreement with the experimental results shown in Fig. 6 (apart from the PBD925/DOP solution – see Section IV.A) as well as with other results.
The results of Tao et al. has been recently proposed by Park et al. and dilution effect of ultra-high diluted in paraffinic oil. The molar mass of such sample is 12. Another interesting example has been recently proposed by Park et al., who studied the dilution effect of ultra-high $M_w$ polyethylene ($M_w > 10^6$ g mol$^{-1}$) diluted in paraffinic oil. The molar mass of such sample is so high that even at the lowest investigated concentration of 2.5 wt%, the sample shows a clear rubbery plateau. In this work also, it was found that the viscoelastic data of this sample in solutions correspond to an effective $z$ of 1.

In this part, it has been shown that the chains containing less than 20 long–long entanglements mainly relax by the CR-CLF process, and their terminal relaxation time, which is well predicted based on $z = 1$, scales with $(c^2Z_{2,o})^4$. The chain equilibration through the CR-CLF process leads to a partial relaxation of the long chains and thus to a decrease of the corresponding level of the storage modulus. This effect is a function of $Z_2$, and is already detected at intermediate frequency in the case of polymer/oligomer blends. This larger dilution effect of the oligomers leads to larger values of the effective $z$, especially for blends with $Z_2 < 12$.

### IV.4. Solutions in a small-molecule solvent versus polymer/oligomer blends

From the examples above, we can conclude that the proposed model leads to a unified picture, which is in good agreement with the experimental data. However, while this picture holds for the different polymer/oligomer blends which have been tested, it does not seem to describe the linear viscoelastic properties of entangled polymers strongly diluted in a small-molecule solvent. This is discussed in this section.

We first focus on the set of solutions proposed by Colby et al., from which an $z$ value of 4/3 has been obtained. These are solutions of polybutadiene chains of mass $M_w = 925$ kg mol$^{-1}$ dissolved in dioctyl phthalate (considered as a theta solvent). Fig. 10 shows the comparison between their experimental and predicted storage modulus. Parameters used in the tube model are the material parameters usually used with the TMA model for polybutadiene samples (i.e. a plateau modulus of 1.2 MPa, $M_z = 1650$ g mol$^{-1}$ and $\tau_\varepsilon = 2.3 \times 10^7$ s) As it can be seen, while the model accurately captures the viscoelastic properties of the higher concentrated solutions (polymer concentration of 100 wt%, 52.3 wt% and 30.6 wt%), it starts to deviate at intermediate concentrations (15.7 wt% and 8.06 wt%), and the deviation becomes very large at very low concentrations (3.08 wt% and 2.14 wt%); it is clear that the level of the predicted plateau modulus is too high compared to the experimental data, despite the fact that the CR-CLF process is taken into account. In fact, as discussed in Section IV.3, this last process becomes really effective only if $Z_2 < 12$, while here, $Z_2 = 17$ and 12 for the solutions at 3.08 wt% and 2.14 wt% respectively (based on $z = 1$).

Also, as observed in Fig. 10, the sample PBD925 diluted at 2.14 wt% shows a viscoelastic behavior close to full relaxation by Rouse (see the dashed curve), as if the long chains were nearly not entangled, which definitely does not correspond to the behavior of a chain containing 12 entanglements. Thus, when highly diluted, these PBD chains seem less entangled.
than the predicted number of entanglements based on $\alpha = 1$ and accounting for CR-CLF. In such a case, using a larger value of the real dilution exponent $\alpha$ could, indeed, lead to better agreement.

However, considering a larger exponent $\alpha$ would have large consequences for the predictions of the viscoelastic properties of the polymer/oligomer blends, which are well described with $\alpha = 1$. We thus face a situation in which our tube model cannot correctly predict the linear viscoelastic properties of both the polymer/oligomer blends and these solutions in a small-molecule solvent. This is illustrated in Fig. 11, which compares a PBD solution of ref. 14, composed of 2.14 wt% of sample PBD925k in DOP, to the polymer/oligomer blend composed of 5 wt% of PBD410 in PBD3:10 although of different composition, these two samples have a similar number of entanglements ($Z_2 = 12$ and 12.4 respectively) if we consider $\alpha = 1$ (by considering $\alpha = 1.3$, $Z_2 = 3.8$ and 5 respectively).

From this figure it is clear that the two solutions have a very different viscoelastic behavior: in contrast to the viscoelastic response of the PBD925k sample diluted in DOP, the response of the PBD410k sample diluted in oligomers strongly differs from a Rouse-like response and is well described by our model with a real $\alpha$ exponent of 1. Furthermore, the level of its plateau could not be captured by considering an $\alpha$ value of 1.3. Indeed, in such a case, the storage plateau would have been 2.5 times lower than the present plateau, which does not correspond to the experimental data.

One can also observe that the two solutions have similar terminal relaxation times, which is somehow surprising since the reptation time of the diluted PBD925k should be higher by a factor of 4.9 (based on $\alpha = 1$) or at least by a factor of 3.8 (based on $\alpha = 1.3$) than the reptation time of the PBD410k/PBD3k blend. This is also seen in Fig. 8b: at low $Z_2$, the terminal relaxation times of the solutions in small-molecule solvents are much shorter than the relaxation times of all polymer/oligomer blends, as if the long chains were less entangled.

Other examples of PS solutions in small-molecule solvents can be found in the literature. In particular, in ref. 34, Bhattacharjee et al. studied the rheology of PS chains of mass $M_w = 3900$ kg mol$^{-1}$ dissolved in diethyl phthalate (DEP), dibutyl phthalate (DBP) or dioctyl phthalate (DOP). However, due to the use of different solvents with different qualities (from good for DEP and DBP, to theta for DOP), it is difficult to determine the origin of the observed discrepancy for this last set of solutions. Another systematic set of data has been presented by Osaki et al.,19 who studied very long PS chains (with $M_w = 2890$, 4480 and 8420 kg mol$^{-1}$) dissolved in a good solvent (chlorinated biphenyl). Similarly to the results found with the PBD solutions, these curves cannot be modelled based on the approach used for the polymer/oligomer blends. This is illustrated in Fig. 12, which compares experimental and predicted curves for the PS solution containing 5 wt% of PS8420: since $Z_2$ is equal to 28 (with $\alpha = 1$), the predicted dilution effect is very small and at intermediate frequency, the storage modulus is close to its rubbery plateau, which has been determined based on $\alpha = 1$. In contrast, we observe that the experimental plateau corresponds rather to an $\alpha$ value close to 1.3, which is the scaling found by Osaki et al., after having removed the high frequency Rouse contribution from the experimental data in order to determine $G_{p,0}^0$.

On the other hand, the shape of the moduli is similar to the ones found for the blend composed of 40% of PS280 in OS8.8 (see the dashed curves compared to the star symbols), i.e. corresponds to long chains with 22 entanglements. For PS8420 diluted at 5 wt%, a value of $Z_2$ equal to 22 corresponds to an $\alpha$ value close to 1.08 (since $8420k/[(M_{e,0},mel/0.05^{1.08}) = 22]$). Thus, for this sample, it seems that the scaling in terms of plateau modulus and relaxation time is different.

The reason why the diluted PBD925k behaves differently compared to the polymer/oligomer blends is not clear and should be further investigated. While it could come from the fact that the solvent used is a small-molecule solvent, which possibly affects the ability of the chains to create entanglements, it could also be due to a difference in the cooperativity between the long chains and the oligomers or the small-molecule solvent: the high-$M$ chains in the small-molecule solvent determine their
entanglement mesh size according to the solubility of the solvent, without any time needed to reach their equilibrium state. Thus, the high-\( M \) chains in those solutions obey the Colby–Rubinstein argument and their plateau modulus is proportional to \( c^{2.3} \) in semi-dilute solutions. In contrast, in the high-\( M \)/oligomer blends, there is a very strong cooperativity between the oligomers and high-\( M \) chains, at least up to the length scale of the oligomer chains, since the motion of the Rouse segments of the high-\( M \) chain occurs together with the motion of the oligomers. Consequently, this strong cooperativity leads to a slower equilibration, which is well described by the CR-CLF process.

In order to validate this proposition, one should compare these data to the viscoelastic behavior of very long chains (similar to PS8420k) blended, in a few percent, with short chains or oligomers and check if their effective \( x \) continues to be equal to 1 until \( Z_c = 12 \) (as the theoretical values shown for PS4000 in Fig. 9a).

V. Conclusions

We have studied and modelled the viscoelastic properties of several polymer/oligomer blends, with various molar masses and concentrations of long chains, in order to discuss the dilution effect from the oligomers on the entanglement state of the long chains. In particular, we have shown that, at low concentration, the effective dynamic dilution exponent determined from the scaling of the level of the storage modulus corresponding to \( G_0 \) or \( G_{\text{max}}' \) with concentration is larger than the real or actual dilution exponent \( x \), which is fixed to 1. This is due to the fast contribution of the CR-CLF process, which can take place without any delay coming from the oligomers. Consequently, in case that the number of (long–long) entanglements of the long chain falls below 12 (by lowering either the molecular weight or the solution concentration), \( G_0 \) is found to scale with \( c^{2.35} \) and cannot be used as a measure of the plateau modulus.

These results are in good agreement with ref. 11, where a larger value of the effective \( x \) in binary blends of linear chains was attributed to the partial re-orientation of the long–long entanglement segments, taking place through the tension re-equilibrium process along the chains. A similar picture is used here to analyze the viscoelastic properties of the polymer/oligomer blends, by considering that the relaxation time of a long–long entanglement segment is well described by its intrinsic Rouse time, with no extra delay due to the motion of the short chains.

While this approach could successfully explain the viscoelastic properties of a large number of polymer/oligomer blends, an important discrepancy was found for semi-dilute solutions of entangled polymers in theta or good solvents: their plateau moduli scaled with \( c^{2.3} \) rather than with \( c^2 \). It has been shown that this behavior was not comparable to the viscoelastic behavior of the polymer/oligomer blends and that we could not describe the moduli of both types of samples with a single tube model. The possible origin of this difference has been proposed, based on the difference in cooperativity between the long chains and the oligomers or the small-molecule solvent.

In perspective, one should study the viscoelastic properties of very long chains (i.e. still entangled when diluted at a few percent) blended with short chains or oligomers, in order to validate our proposition. This question needs, indeed, to be solved if we want to compare the extensional behavior of these different blends and solutions.

Acknowledgements

The authors thank Prof. Hiroshi Watanabe for very helpful discussions and suggestions, Dr Meik Ranft (BASF Ludwigshafen, Germany) for the determination of molecular weight distribution of the PS820 sample, and the People Programme (Marie Curie Actions) of the European Union’s Seventh Framework Programme (REA grant agreement no. 607937). This work was funded by DSM Ahead (for T. S.), the Aage and Johanne Louis-Hansen foundation (for Q. H.) and the F. N. R. S. (for E. V. R. as chercheur qualifié).

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